

Abstract

The invention is directed to acquiring and processing parameters used to adjust and tune a controller used, for example, to govern and compensate for motion, including vibrations and disturbances, in a physical system, such as a piece of manufacturing equipment. The invention may also be used to control, for example, a robot or other spatially dependent machine. Included in the invention are systems and methods for generating a controller, and for controlling motion in a physical system or apparatus.

10